



DESIGN AND ANALYSIS OF ALGORITHMS (DAA) (A34EC)

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Experiment Design



Implement





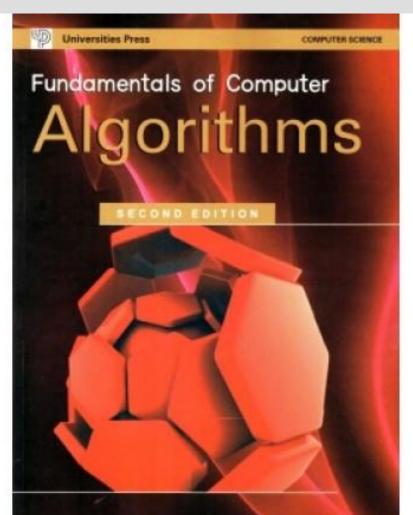












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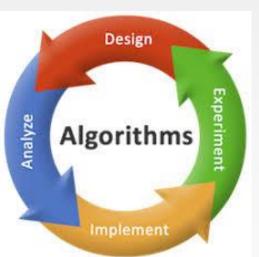


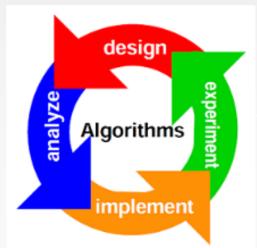






DAA Unit VI NP-Hard and NP-Complete Problems











NP-Hard and NP-Complete Problems:

- **Basic Concepts**
- Nondeterministic Algorithms
- NP-Hard and NP-Complete Classes
- Cook's Theorem.







Basic Concepts



- In this unit, we are going to learn distinction between problems that can be solved by a polynomial time and problems for which no polynomial time algorithm is known.
- It is unexplained phenomenon that for many of the problems we know and study, the best algorithm for their solutions have computing times that cluster into two groups.
- The first group consists of problems whose solution times are bounded by polynomials of small degree like Linear Search O(n), Binary Search O(log n), Bubble/Insertion sorting O(n²), Merge Sorting O(n log n), Matrix Multiplication O(n³) etc.
- The second group is made up of problems whose best-known algorithms are nonpolynomial (exponential) like Travelling Salesperson O(n²2ⁿ) and 0/1 Knapsack Problem O(2ⁿ), Sum of Subsets O(2ⁿ), Graph coloring O(2ⁿ), Hamiltonian Cycle O(n²2ⁿ), etc.



Basic Concepts



- In the quest to develop efficient algorithms, no one has been able to develop a polynomial time algorithm for any problem in second group.
- This is very important because algorithms whose computing times are greater than polynomial (specially time is exponential) very quickly require such vast amount of time to execute that even moderate-size problems cannot be solved.
- Here we are going to show that many of the problems for which there are no known polynomial time algorithms are computationally related.
- In fact, we establish two classes of problems, namely NP – Hard and NP – Complete.



Basic Concepts



- A problem that is NP Complete has the property that it can be solved in polynomial time if and only if all other NP – Complete problems can also be solved in polynomial time.
- If an NP Hard problem can be solved in polynomial time, then all NP – Complete problems can be solved in polynomial time.
- All NP Complete problems are NP Hard, but some
 NP Hard problems are not known to be NP Complete.



Nondeterministic Algorithms



- Generally, algorithms has the property that the result of every operation is uniquely defined.
- Algorithms with this property are called **Deterministic** Algorithms.
- Such algorithms represent the programs which can be executed on a computer.
- In a theoretical framework we can remove this restriction on the outcome of every operation.
- We can allow algorithms to contain operations whose outcomes are not uniquely defined but are limited to specified sets of possibilities.
- The machine executing such operations is allowed to choose any one of these outcomes subject to termination condition to be defined later.



Nondeterministic Algorithms



- These types of Algorithms are called Nondeterministic Algorithms.
- To specify such algorithms, we introduce three new functions:
 1. Choice(S) arbitrarily chooses one of the elements of set S.
 - 2. Failure() indicates an unsuccessful completion.
 - 3. Success() indicates an successful completion.
- 4 The assignment statement $x \coloneqq Choice(1, n)$ could result in x being assigned any one of the integers in the range [1, n].
- Whenever there is a set of choices that leads to a successful completion, then one such set of choices is always made and the algorithm terminates successfully.
- A nondeterministic algorithm terminates unsuccessfully if and only if there exists no set of choices leading to a success signal.



Nondeterministic Algorithms



- The computing time for Choice, Success and Failure are taken to be O(1).
- A machine capable of executing nondeterministic algorithm is called a nondeterministic machine.
- Although nondeterministic machine do not exists in practice, we see that they provide strong intuitive reasons to conclude that certain problems cannot be solved fast deterministic algorithms.
- ▲ Example 1 Nondeterministic Search (NSearch): Consider the problem of searching for an element *x* in a given set of elements *A*[1: *n*], *n* ≥ 1.
- We have to find an index j such that A[j] = x or j = 0 if x is not in A.

- A nondeterministic algorithm for this is
- 1. Algorithm NSearch (Am n, x)
- 2.
- 3. $j \coloneqq Choice(1, n); // j$ is assigned value between 1 and n
- 4. if A[j] = x then
- 5. // By luck, if j is the index of our searching element x
 6. {
- 7. write (j); // Then display the position of the element
- 8. Success(); // Non deterministic algorithm is
- 9. // successfully executed & terminates
- *10.* }
- 11. write (0); // Then display the 0 as position of
- *12. // the element indicating failure.*
- *13.* Failure(); // Non deterministic algorithm is
- 14. // failed and terminates
- *15.* }

From the way of a nondeterministic computation is defined, it follows that the number 0 can be output if and only if there is no *j* such that A[j] = x.

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- **4** Search Algorithm is of nondeterministic complexity O(1).
- Note that since A is not ordered, every deterministic search algorithm is of complexity $\Omega(n)$.
- **4 Example 2 Nondeterministic Sorting (NSort)** : Let *A*[*i*], 1 ≤ *i* ≤ *n*, be an unsorted array of positive integers. The nondeterministic algorithm *NSort*(*A*, *n*) sorts the numbers into increasing order and then output them.
- 4 An auxiliary array B[1:n] is used for convenience.
- **4** The time complexity is O(n).
- 4 Recall that all deterministic sorting algorithms must have a complexity of Ω(*n log n*).

- 1. Algorithm NSort (A, n)
- 2. // Sort n positive integers.
- *3.* {
- 4. for $i \coloneqq 1$ to n do $B[i] \coloneqq 0$; // Initialize array B[] with 0
- 5. for $i \coloneqq 1$ to n do
- *6.* {
- 7. $j \coloneqq Choice(1, n);$
- 8. // j is assigned a value between 1 and n
- 9. if $B[j] \neq 0$ then
- 10. // if j value is already chosen value, then failure11. Failure();
- 12. $B[j] \coloneqq A[i];$

13. // Assign B[j] as next element from array A, A[i]
14. }

15. for $i \coloneqq 1$ to n - 1 do // Verify the sort order. 16. if B[i] > B[i + 1] then

- *17. // If elements chosen not in correct sorted order*
- 18. Failure(); // Algorithm unsuccessfully terminates
- 19. write (B[1:n]); // If elements are by luck,
- 20. // chosen in correct sorted order, then display.
- 21. Success(); // Algorithm successfully terminates
 22. }
- **4** *Example*: n = 4 $A[] = \{5, 9, 7, 2\}$
- **4** Successful Case : Randomly choose j = 2, 4, 3, 1

$$\blacksquare B[2] = A[1] = 5$$

- + B[4] = A[2] = 9
- **↓** B[3] = A[3] = 7
- + B[1] = A[4] = 2
- *Display B***[] = { 2, 5, 7, 9 }**

Example 3 - Nondeterministic 0/1 Knapsack Problem :

- 1. Algorithm NKP (p, w, n, m, r, x)
- *2.* {
- 3. $W \coloneqq 0$; $P \coloneqq 0$; $//No \ objects \ are \ chosen \ yet$
- 4. for $i \coloneqq 1$ to n do
- **5.** {
- 6. $x[i] \coloneqq Choice(0, 1);$
- 7. // Object i, is randomly decided to chose or leave
- $\mathcal{B}. \qquad W \coloneqq W + x[i] * w[i];$
- 9. // If Object i is chosen, then add its weight, else add 0
- 10. $P \coloneqq P + x[i] * p[i];$ // similarly, If Object i is
- 11. // chosen, then add its profit, else add 0.
- *12.* }





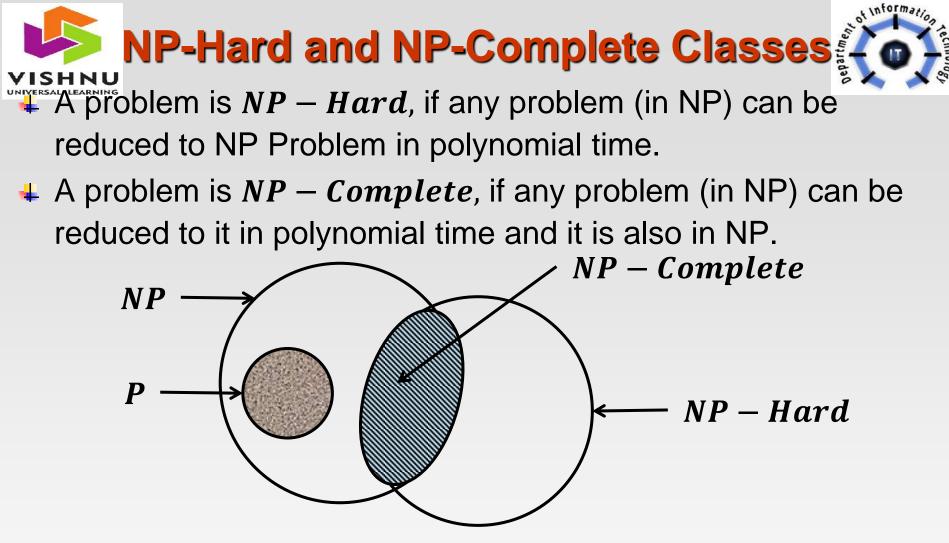


- 13. if ((W > m) or (P < r)) then
- 14. //If selected objects weight is more than Knapsack
- 15. //capacity or selected objects won't give us
- 16. //maximum profit r.
- *17. Failure()*;
- 18. // Algorithm unsuccessfully terminates.
- 19. else Success();
- 20. // Otherwise Algorithm successfully terminates.
 21. }
- **4** The time complexity is O(n).
- 4 If q is the input length using binary representation, the time is O(q).

NP-Hard and NP-Complete Classes

Definition *P*, *NP*, *NP* – *Hard* and *NP* – *Complete*

- In measuring the complexity of an algorithm, we use the input length as parameter.
- An algorithm A is of Polynomial Complexity if there exists a polynomial p() such that the computing time of A is O(p(n)) for every input of size n.
- P is the set of all decision problems solvable by deterministic algorithms in polynomial time.
- **NP** is the set of all decision problems verifiable by Nondeterministic Algorithms in polynomial time.
- If a problem & solution is given, algorithm should be able to tell correct or incorrect in polynomial time.
- ▲ Since deterministic algorithms are just a special case of nondeterministic, we conclude that $P \subseteq NP$.



♣ This means, the set of NP – Complete problems is the set formed by intersect of NP and NP – Hard.

↓ The main ambiguity in computer science field is whether $P = NP \text{ or } P \neq NP$.

NP-Hard and NP-Complete Classes



NP

- It is possible that for all problems in NP, there exists polynomial time deterministic algorithms that have remained undiscovered?
- This seems unlikely, at least because of the tremendous effort that has already been extended by so many people on these problems.
- ▲ A proof that $P \neq NP$ is just as elusive and seems to require as yet undiscovered techniques.
- **↓** But as with many famous unsolved problems, they serve to generate other useful results, and the question of whether $NP \subseteq P$ is no exception.
- ↓ The figure displays the relationship between P and NP assuming $P \neq NP$.



Cook's Theorem



- S. Cook formulated the following question : Is there any single problem in NP such that if we showed it to be in P, then that would imply that P = NP?
- Cook answered his own question in the affirmative with the following theorem, known as Cook's Theorem.
- **4** Cook's Theorem : Satisfiability is in P if and only if P = NP
- *NP Hard and NP Complete* : A Problem L is in *NP Hard*, if and only if satisfiability reduces to L (satisfiability ∝ L)
- ▲ A problem L is NP Complete if and only if L is NP Hardand $L \in NP$.
- The satisfiability problem is determine whether a formula is true for some assignment of truth values to the variables.



Cook's Theorem



Satisfiability : Nondeterministic approach

- 4 Consider a problem with 4 variables $x_1, x_2, x_3, and x_4$
- Let conjunctive normal form of the problem is

 $E = (x_1 \lor \overline{x}_3) \land (\overline{x}_2 \lor x_3 \lor \overline{x}_4) \land (x_2 \lor \overline{x}_4)$

- 4 This function E, will be true if and only if every ax term is true.
- The expression E is valid only when if it is true for all true values of its variables x₁, x₂, x₃, and x₄.
- This can be written using Nondeterministic Algorithm

Nondeterministic Satisfiability Algorithm :

- 1. Algorithm Eval(E, n)
- 2. //Determine whether the propositional formula E
- 3. //is Satisfiable the variables are $x_1, x_2, x_3, \dots, x_n$. 4. {
- 5. for $i \coloneqq 1$ to n do
- 6. // Choose a truth value assignment.
- 7. $x[i] \coloneqq Choice(false, true);$
- 8. // Variable x[i], is randomly chosen 0 or 1

9. if $(E(x_1, x_2, x_3, ..., x_n) = 1)$ then // If chosen values 10. // of all variables x[] satisfies the given Expression E

- 11. Success(); // Algorithm successfully terminates.
- *12. else*
- *13. Failure()*;
- 14. // Otherwise, Algorithm unsuccessfully terminates
 15. }



The above algorithm chooses one of the 2ⁿ possible assignments of truth values to (x₁, x₂, x₃, ..., x_n) and verifies that E(x₁, x₂, x₃, ..., x_n) is true of not for that assignment in nondeterministic approach.





BEST OF LUCK FOR YOUR MID AND FINAL EXAMINATIONS

